



TOYOTA
RESEARCH INSTITUTE

Welcome to TRI



Welcome to TRI

10:00-10:05	Greeting and Intros
10:05-11:05	TRI Overview Robotics Overview Tour of Robotics Lab
11:05-11:35	SIC Overview
11:35-11:45	Break/walk to lunch
11:45-12:45	Lunch



TRI Overview

Eric Krotkov

TOYOTA

Toyota Research Institute

“We are rapidly accelerating our pace in advancing Toyota’s automated driving capabilities with a vision of saving lives, expanding access to mobility, and making driving more fun and convenient.”

Gill Pratt

CEO, Toyota Research Institute
Fellow, Advanced R&D Company,
Toyota Motor Corporation



Quick Facts

~\$300M/yr

Budget

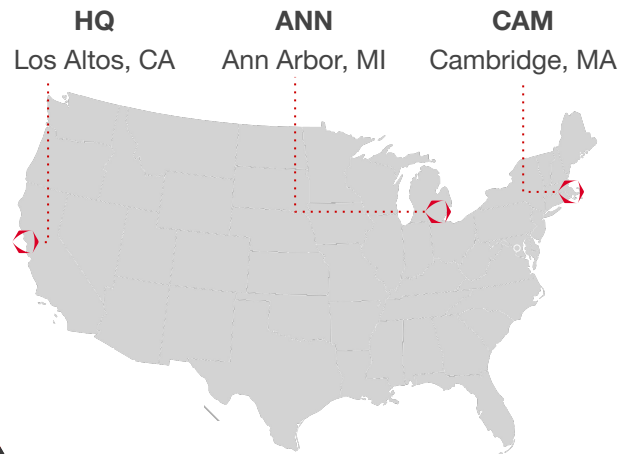
~ 300

Employees

3

sites

- Established in January 2016
- What we do: Automated driving, Robotics, Exploratory research
 - Leadership with experience from key government agencies & companies
 - 45% of R&D staff hold PhD degrees
- Three facilities in Cambridge, Ann Arbor, & Silicon Valley
- Working closely with related Toyota Companies:



TRI: Our Leadership Team

Dr. Gill Pratt
CEO



Kelly Kay
EVP & CFO



Dr. Eric Krotkov
CSO



Dr. Ryan Eustice
SVP, Automated Driving



Max Bajracharya
VP, Robotics



Jen Cohen
VP, Operations



Dr. Wolfram Burgard
VP, Automated Driving Tech.



Dr. John Leonard
VP, Risk Awareness



Dr. Russ Tedrake
VP, Robotics Research



Steve Winston
VP, Software Platform



Justin Kida
Resident Board Member



Suzanne Basalla
Chief of Staff

TRI: Our People & Culture



What We Do



AUTOMATED DRIVING

Two-track development approach:

Chauffeur: full autonomy where the human is essentially removed from the driving equation

Toyota Guardian: amplifies human vehicle control, not replace it



ROBOTICS

Developing intelligent, capable, & assistive robots that improve the quality of human life & extend people's independence



EXPLORATORY RESEARCH

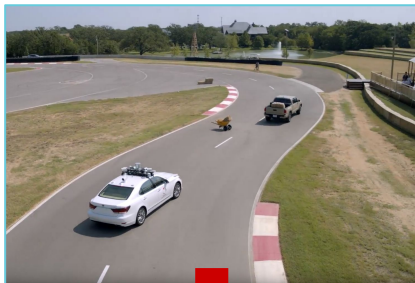
**ACCELERATED
MATERIAL
DESIGN &
DISCOVERY**

**MACHINE
ASSISTED
COGNITION**

**UNIVERSITY
COLLABOR-
ATIONS**

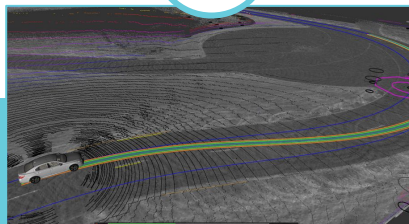
TRI Aims to Transform the Human Condition

Safety



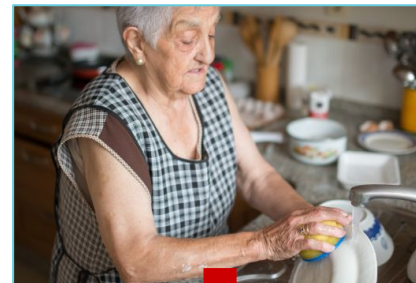
Guardian

Access



Chauffeur

Quality of Life



Robots

Automated Driving Approach: One System, Two Modes

GUARDIAN



CHAUFFEUR

Driver always engaged, but vehicle monitors and intervenes to help prevent collisions

Builds on similar hardware and software development as fully-autonomous Chauffeur

Fully autonomous driving system engaged at all times

Staged commercial release, likely beginning with shared mobility fleets

Robotics

Enabling intelligent,
physically-capable,
& socially-assistive
robots



Situational
Awareness

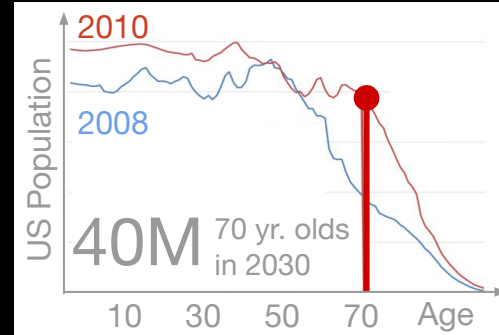


Manipulation

*Source: IFR World Report, METI/NEDO, Tractica,
BCG, P&S Market Research, Dream Incubator



Global Trend



US Population Age over 65

Today: 13% 2030: 20%

Japan Population Age over 65

Today: 20% 2035: 40%

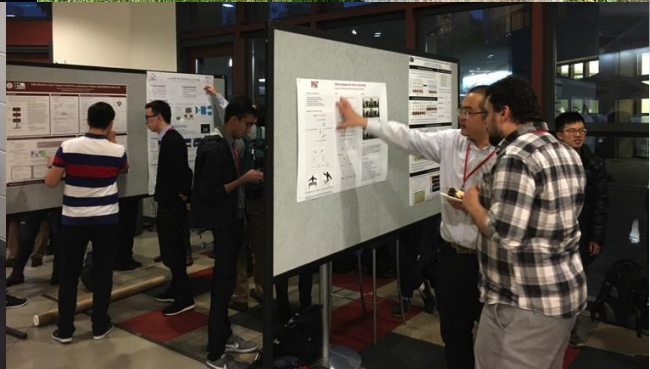
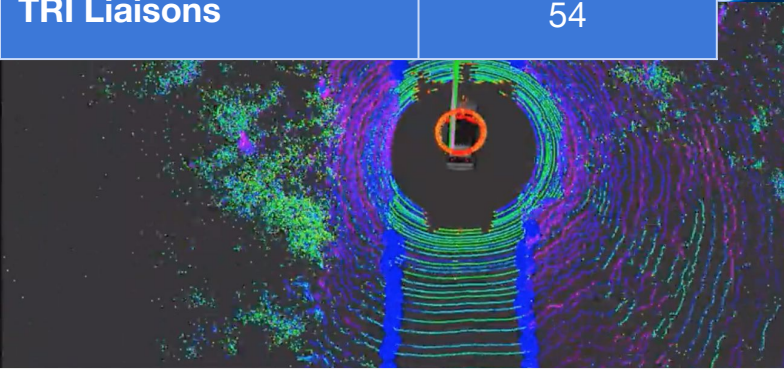
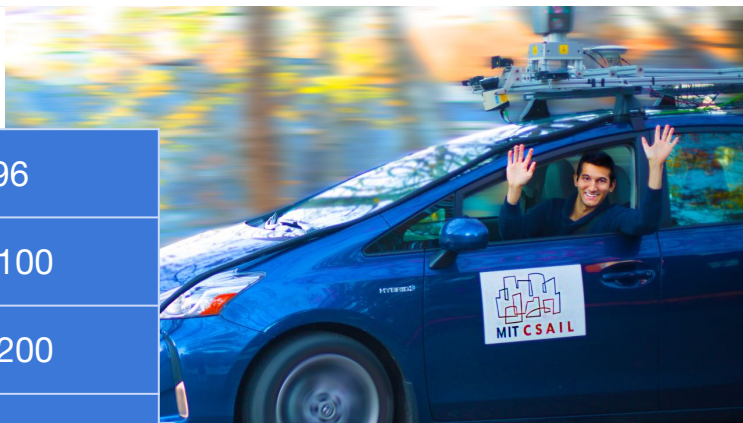
Global Robots Market

2020: \$68B 2030: \$400B

University Research Program



Projects	96
Faculty	> 100
Students & Postdocs	> 200
TRI Liaisons	54



Program Outputs (Through July 2019)

	Interns	Hires	Papers	Patent Filings
Stanford	10	4	146	12
MIT	3	6	116	16
Michigan	8	8	54	5
Totals	21	18	316	33

CVPR 2018 Best Paper. ICRA 2019 Best Paper
ICRA 2019 Finalist Best Paper

AMDD

(Accelerated Material Design & Discovery)

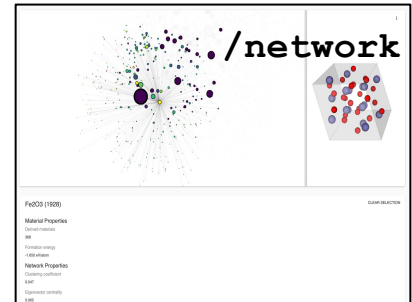
Applying AI to
accelerate discovery of
advanced materials for
future mobility



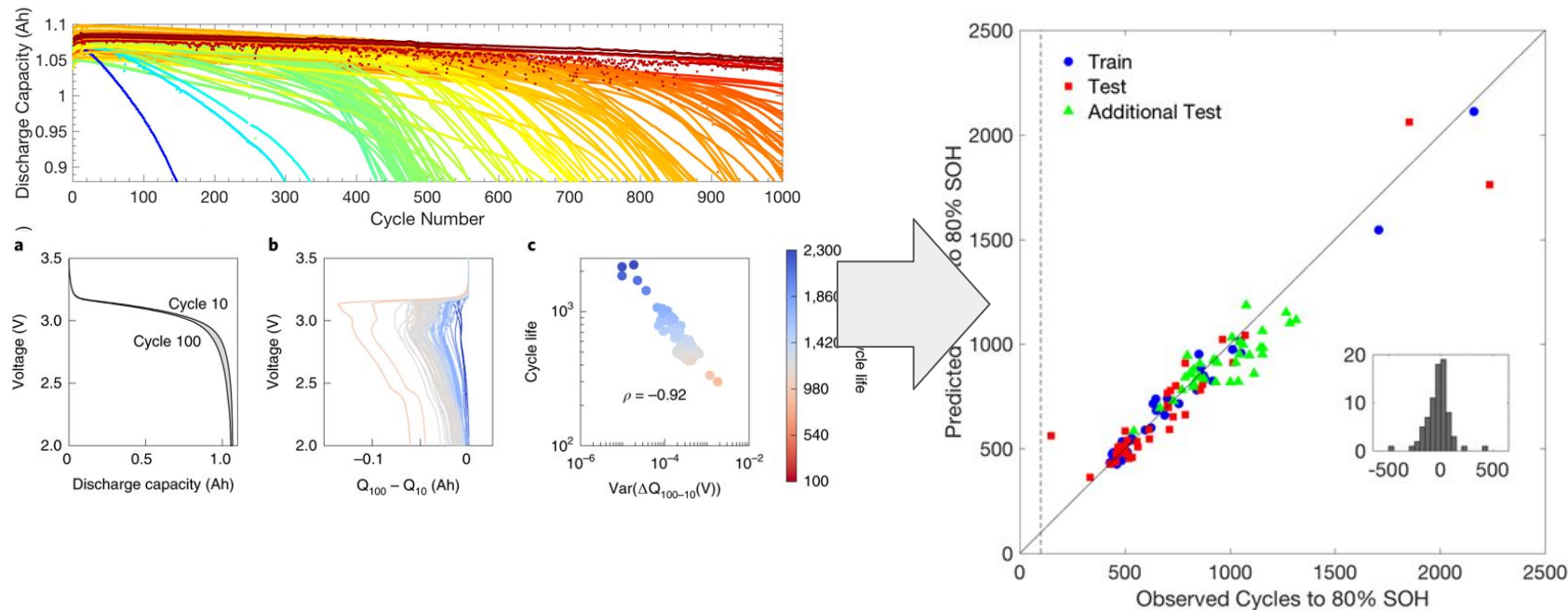
New Tools for advancing
batteries and fuel cells



Collaborating with
universities, research
entities, & companies
(~\$35M over 4 years)



BEEP predicts battery cycle life quickly



Data driven prediction of battery cycle life before capacity degradation. Nature Energy, 2019.

Machine Assisted Cognition (MAC)

Develop and demonstrate computational aids to amplify and augment human cognitive abilities

- Computational aids - AI-powered software systems that directly assist users with tasks requiring careful, deliberate thought
- Cognitive abilities - Prediction, judgment, decision making
- Amplify and augment - The goal is not to imitate or replace human abilities; instead, the goal is to leverage and extend them



TRI Robotics

Russ Tedrake

Robotics Capabilities - Manipulation



Robotics Capabilities - Fleet Learning



私たちの方法は、実験室、実際の家庭といった多様な環境下においても、
さまざまなタスクを遂行できる有効なアプローチです。



Thank You